

Robotic Systems JPO



Jeffrey Jaczkowski
Deputy Project Manager

Currently, he serves as the Deputy Project Manager for the Robotic Systems Joint Project Office (RS JPO) under the Program Executive Office for Ground Combat Systems (PEO GCS). He is responsible for developing, acquiring, fielding and sustaining ground robotics for the Army and USMC.

He began his Government service as a co-op student in 1988 at the U. S. Army Tank Automotive Research, Development and Engineering Center (TARDEC) at the Detroit Arsenal in Warren, Michigan. While co-op'ing, he earned his Bachelor of Science degree in electrical engineering from GMI Engineering and Management Institute, Flint, MI (1993). Upon graduation in June 1993, he became an intern rotating through various TARDEC Business Groups gaining experience in systems engineering, technology integration and defense acquisition.

In 1995, Mr. Jaczkowski completed his internship and worked as an electrical engineer in the Vetronics Technology Area for the Driver's Automation & Robotics Team where he led and performed field integration of Intelligent Transportation Systems (ITS) consisting of Collision Warning Systems (CWS) and Intelligent Cruise Control. This resulted in the fielding of a collision warning capability as a safety system for Army tactical wheeled vehicles.

Mr. Jaczkowski earned his Master of Science degree in engineering management from Oakland University, Rochester, MI (1997).

From 1998-2003, as Team Leader for Robotics, Mr. Jaczkowski was responsible for project development, planning and management, customer interface, budget monitoring and execution. He served as IPT chairman for Future Combat Systems (FCS) Unmanned Systems Working Group, comprised of multiple Government agencies, responsible for coordinating a concept development effort with system level programs, defining robotic system metrics, conducting technology trade studies and evaluating technical concepts.

In 2003, Mr. Jaczkowski was appointed a member of the Army Acquisition Corps.

From April 2003 to May 2007, Mr. Jaczkowski was Team Leader for RDEDOM –TARDEC's Autonomous Navigation Team where he managed the Robotic Follower Advanced Technology Demonstrator (ATD) and Science and Technology Objective (STO) program and led a team of robotics subject matter experts analyzing a variety of functional and cross discipline areas for the advancement of unmanned ground vehicle performance and operation.

In March 2006 (through April 2008), MG Roger Nadeau appointed Mr. Jaczkowski as Co-chair of the RDECOM Robotics IPT responsible for aligning Army Science and Technology development efforts with customer requirements, facilitating multi-organization cooperation, guiding S&T development from concept to experimentation, and defining the path forward for transition to PEO/PM programs of record, including the Robotic Systems Joint Program Office.

From May 2007 to May of 2008, Mr. Jaczkowski served as Supervisor Deputy Associate Director (Engineering) of the Intelligent Ground Systems Technology Area responsible for organizational leadership, personnel supervision and career mentoring, program formulation, prioritization of projects and milestones, resource and financial management and technical execution of autonomous systems efforts. He completed the Advanced Acquisition Program at the Naval Postgraduate School in September 2007 and is Level III qualified for Program Management. He also serves as President of the Great Lakes Chapter of the Association for Unmanned Vehicle Systems International (AUVSI) (2004-present).